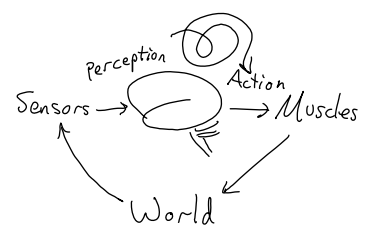
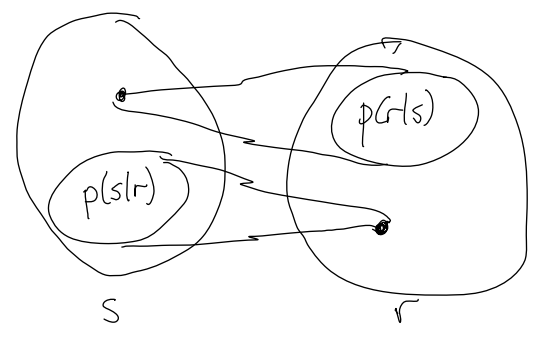


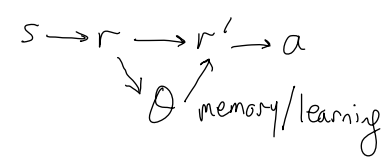
GOALS of Neural Computation



Sensory systems gather information about World



Encoding $p(r|s)$ Decoding $p(s|r)$ Recoding $p(r'|r)$ Acting $p(a|r)$



Next 1/2 semester:

Goals of computation (today)

What networks do

- linear
- nonlinear
- stochastic

How networks compute

- feedforward (linear, nonlinear)
- recurrent
- probabilistic

Encoding

Responses r generated probabilistically

Single neuron examples

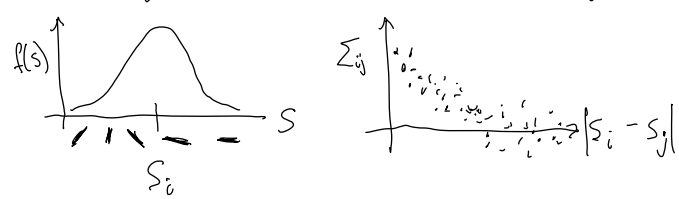
$$p(r|s) = \begin{cases} \lambda & r=1 \\ 1-\lambda & r=0 \end{cases} \text{ Bernoulli}$$

$$p(r|s) = \frac{e^{-\lambda} \lambda^r}{r!} \text{ Poisson}$$

$$p(r|s) = \frac{e^{-\frac{r-\mu}{\sigma}}}{\sqrt{2\pi}\sigma^2} \text{ Gaussian}$$

Experiments: choose s , measure/model r
often compute $\langle r|s \rangle = f(s)$ = tuning curves
 $\langle r_i r_j | s \rangle = \sum_i \langle r_i | s \rangle \langle r_j | s \rangle$ = noise correlations

more generally, find $p(r|s)$, but this is high-D



Why is this useful?

- nontrivial tuning suggests s is important for these neurons
- try to reconstruct s ?
- compute posterior $p(s|r)$?

Limitations: restricted s

- unnatural context (eg. not full image)
- static
- maybe not the most relevant feature

Receptive fields

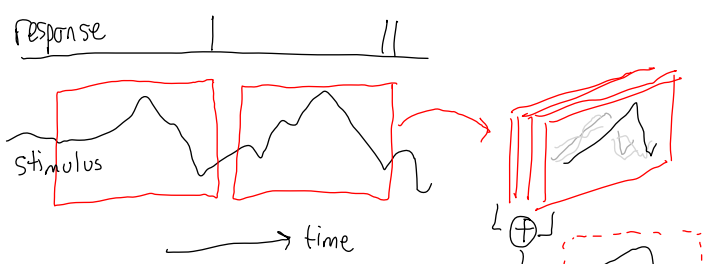
Generalize tuning to higher-D: $p(r|I)$

Problem: even for one neuron this is huge.

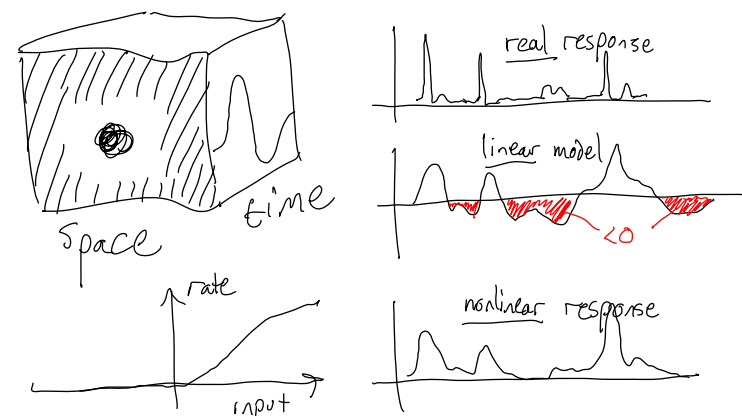
Solution: use model for moments

$$p(r|I) \rightarrow \langle I \rangle = \text{STA (linear model)}$$

$$\rightarrow \langle s_i s_j | I \rangle = \text{STC (quadratic model)}$$



STA = Spike Triggered Avg



Many more complex encoding models



Decoding

What does the decoder know?

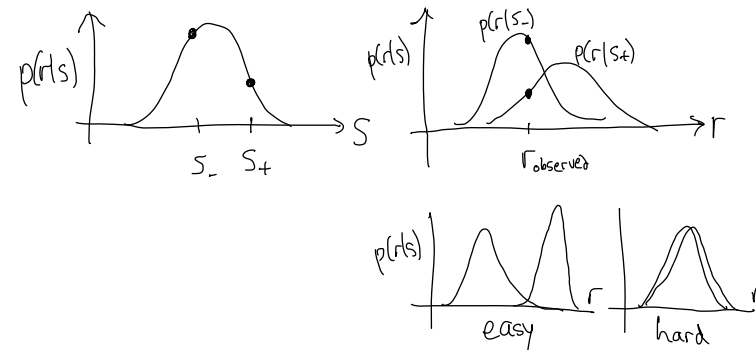
- prior distribution of s ? Bayesian
- only knows $p(r|s)$? Frequentist ← first

Brain needs to interpret $r \Rightarrow p(r|s)$ (likelihood)

How to characterize quality of $p(r|s)$?

{discriminate, estimate, calculate uncertainty}

- discriminate: $p(r|s_+) \neq p(r|s_-)$



- estimate: $\hat{s} = \arg \max_s p(s|r)$ (Max Likelihood)

$$\hat{s} = w \cdot r + b \text{ (linear estimator)}$$

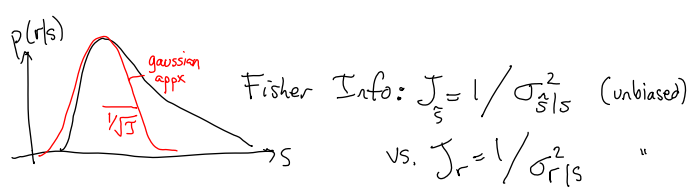
$$\hat{s} = g(r) \text{ (your brain's favorite fn)}$$



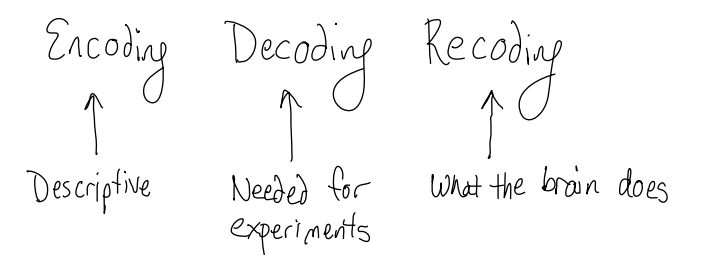
How good is the estimator? $p(\hat{s}|s)$ vs. $p(r|s)$

accuracy: $\langle \hat{s} | s \rangle \neq s \Rightarrow \text{bias}$

precision: $\sigma_{\hat{s}}^2 = \langle \delta \hat{s}^2 | s \rangle$



Summary



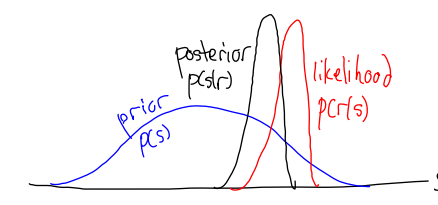
Information always decreases $I_{s;r} \geq I_{s;r'}$
But accessible info increases! $I_{s;\hat{s}(r)} < I_{s;\hat{s}(r')}$

This is because estimators have limited capability and information is represented in a complicated way.

This is neural computation!

Now: use prior knowledge $p(s)$

posterior $p(s|r) \propto p(r|s)p(s)$ (Bayes' rule)



Can still measure variance $\sigma_{s|r}^2$

What is average quality over $p(s)$?

Natural measure is Mutual (Shannon) Information

Information for one event with prob. = p :

$$I(s) \geq 0$$

$$I(s) = 0 \text{ when independent} \Rightarrow I(p) = -\log p$$

$$* I(p, p_2) = I(p_1) + I(p_2)$$

$$I(p) \text{ is continuous}$$

$$\text{Average information } H(p(s)) = \langle -\log p(s) \rangle$$

$$\text{"Entropy"} = -\sum_s p(s) \log p(s)$$

If measurements are noisy, then info is change in uncertainty:

$$I_{R;s} = H(s) - H(s|r)$$

$$L = \langle H(p(s|r)) \rangle_{p(s)}$$

Mutual info, because

$$I_{R;s} = H(s) - H(s|r)$$

$$= I_{s;r} = H(s) - H(s|r)$$

$$= H(s) + H(r) - H(s,r)$$

$$= H(s) + H(r) - H(s,r)$$

$$\text{Examples: } p(x) = \begin{cases} \frac{1}{2} & x=0 \\ \frac{1}{2} & x=1 \end{cases} \Rightarrow H(x) = 1$$

$$p(x) = \frac{1}{N} \forall x \in \{1, \dots, N\} \Rightarrow H(x) = ?$$

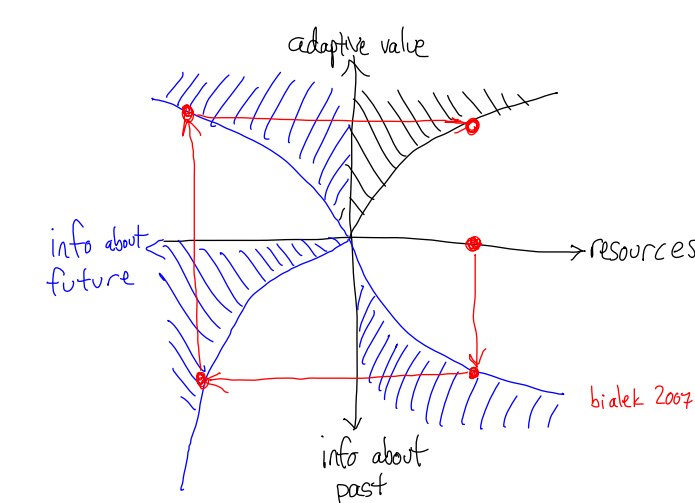
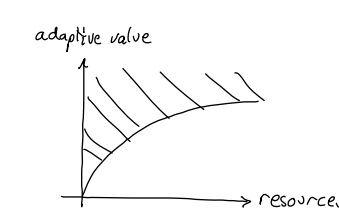
$$p(x) = \begin{cases} q & x=0 \\ 1-q & x=1 \end{cases} \Rightarrow H(x) = ?$$

$$p(x,y) = \begin{matrix} & 0 & 1 \\ 0 & 1/2 & 1/2 \\ 1 & 1/2 & 1/2 \end{matrix}$$

$$p(x,y) = \begin{matrix} & 0 & 1 \\ 0 & 1/4 & 1/4 \\ 1 & 1/4 & 1/4 \end{matrix}$$

$$H(x,y) = -2 \left(\frac{2}{8} \log \frac{2}{8} + \frac{1}{8} \log \frac{1}{8} \right) \approx 1.8$$

Information about what?



Encoded information should be useful, ie predictive: $I_{\text{past}; \text{future}}$

This can be about slowly-changing things, and can be represented in either activity or synapses...

Throw away the rest of the information
This is COMPUTATION.

Brain does not operate on \hat{s} or $p(\hat{s})$ or $p(s|r)$. It operates on r

$r \rightarrow r'$ "Recoding"

That is our main topic.